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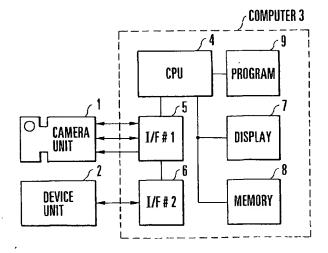
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# (54) Image pickup system and picked-up image signal processing apparatus

(57) In an image pickup system, an image pickup unit is connected to a computer which has a display device. In order to make a display by matching the characteristic of the image pickup unit with that of the display device, the image pickup unit is provided with a control part which is arranged to measure a signal processing speed of the computer, to compare the signal processing speed with an image pickup speed or a picked-up image data output speed of the image pickup unit and to vary an image pickup action or a picked-up image data output action of the image pickup unit according to a result of the comparison or according to an operation performed by an operator of the image pickup system.

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**EP 0 756 225 A2** 

### Description

Background of the Invention:

5 Field of the Invention:

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The present invention relates to an image pickup system in which an image pickup unit is connected for use to an external apparatus arranged to process images.

10 Description of the Related Art:

Computers having connection terminals of the PCMCIA standards are generally arranged to be usable with cardshaped units of various functions inserted therein as a facsimile, a memory, etc. The connection terminal permits use of each of the various card-shaped units by replacing one with another so long as they meet the PCMCIA standards. The connection terminal thus permits selective use of card-shaped units of various functions as desired by the operator.

Fig. 7 shows by way of example an image pickup system which is composed of a computer having the abovestated connection terminal and an image pickup unit which is removably attachable to the computer.

The illustration of Fig. 7 includes a card-shaped image pickup unit 21, computers 22, 24 and 26 which are usable in the image pickup system, and connection terminals 23, 25 and 27 which are respectively arranged to connect the image pickup unit 21 to the computers 22, 24 and 26. A case where the image pickup system is formed by connecting the image pickup unit 21 to the connection terminal 23 is first described as follows.

Referring to Fig. 7, an image is picked up by an optical system and a CCD which are included in the image pickup unit 21. The image picked up is converted into digital image data. The picked-up image data thus obtained is transferred through the connection terminal 23 to the computer 22 at a predetermined speed.

The image pickup unit 21 sends the picked-up image data which includes a color signal to the computer 22 at a rate of n frames per sec. The computer 22 then processes the n-frames/sec picked-up image data sent from the image pickup unit 21 and is capable of displaying the picked-up image data on a built-in color display device or recording the picked-up image data in a built-in recording device.

The use of the computer 22 may be replaced with the use of the computer 24. The computer 24 is provided with the connection terminal 25 which conforms to the same standards as the connection terminal 23 of the computer 22 and a color display device which is similar to that of the computer 22.

Since the connection terminal 25 is of the same specifications as the connection terminal 23, the image pickup unit 21 can be connected to the connection terminal 25. With the image pickup unit 21 connected to the connection terminal 25, the computer 24 displays and records the picked-up image data obtained from the image pickup unit 21 in the same manner as when the image pickup unit 21 is connected to the computer 22.

The operator of the image pickup system can use either the computer 22 or the computer 24 and also can use the image pickup unit 21 in common with them.

This arrangement of the image pickup system, however, has presented the following problems.

In the image pickup system shown in Fig. 7, a case where the computer 26 is used will be considered. The computer 26 has a less amount of consumption of electric power and less weight than the computers 22 and 24, but has a slower processing speed than the computers 22 and 24 and has only a monochrome display device instead of a color display device.

Since the connection terminal 27 also conforms with the same standards as the connection terminals 23 and 25, the computer 26 is capable of exchanging data with the image pickup unit 21 as connected to the connection terminal 27. However, since the processing speed of the computer 26 is too slow, it is impossible to completely process the picked-up image data being sent from the image pickup unit 21. As a result, the picked-up image data tends to be lost in part or an image pickup operation sometimes comes to a stop.

Besides, in such a case, it is impossible to utilize color information included in the picked-up image data sent from the image pickup unit 21 as the computer 26 is provided with only a monochrome display device.

Summary of the Invention:

The present invention is directed to the solution of the above-stated problem of the prior art. It is, therefore, a concern of the invention to provide an image pickup system which is composed of at least one image pickup unit and at least one computer and a picked-up image signal processing apparatus, which are capable of utilizing the characteristics and performance of the computer to a maximum extent and also capable of solving the problems caused by a difference in data processing speed and in display device between one computer and another.

Thus an embodiment of an image pickup system according to the invention may be configured as follows

(1) An image pickup system is composed of an image pickup unit which has a connection terminal for connection with an external apparatus and which is arranged to pick up an image to output picked-up image data from the connection terminal and at least one external apparatus which is connected to the image pickup unit. The image pickup unit comprises data exchange means for exchanging data with the external apparatus connected, processing-speed detection means for measuring or predicting a processing speed of the external apparatus connected, speed comparison means for making a comparison between the processing speed of the external apparatus detected by the processing-speed detection means and an image pickup speed or a picked-up image data output speed of the image pickup unit, and varying control means for varying an image pickup action or a picked-up image data output action of the image pickup unit according to a result of the comparison made by the speed comparison means or according to an operation performed by an operator of the image pickup system.

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- (2) An image pickup system is arranged to include, in addition to the arrangement of the system defined by Para. (1) above, informing means for informing one of or all of the operator of the image pickup system, the external apparatus and the image pickup unit of the result of the comparison made by the speed comparison means.
- (3) An image pickup system is arranged to include, in addition to the arrangement of the system defined by Para.
  (1) or (2) above, Dm detection means for measuring or predicting a maximum amount Dm of picked-up image data transferable per unit time to the external apparatus connected, and data amount comparison means for making a comparison between the detected maximum amount Dm of picked-up image data and an amount Sp of picked-up image data being outputted per unit time by the image pickup unit.
- (4) An image pickup system is arranged to include, in addition to the arrangement of the system defined by Para.
  (1) or (3) above, operation clock detection means for measuring or predicting an operation clock speed of the external apparatus. In the system, the speed comparison means compares the image pickup speed of the image pickup unit with the operation clock speed of the external apparatus measured or predicted by the operation clock detection means
- (5) In the image pickup system defined by any one of Para. (1) to (4) above, when the image pickup unit obtains a plurality of pixel data, the varying control means selects and outputs at least one pixel data from among the plurality of pixel data.
- (6) In the image pickup system defined by any one of Para. (1) to (5) above, the varying control means is arranged to vary the number of frames of images to be picked up per unit time by the image pickup unit.
- (7) In the image pickup system defined by any one of Para. (1) to (6) above, the varying control means is arranged to select and output picked-up image data for at least one picture from among picked-up image data for a plurality of pictures being sent out at intervals of a predetermined length of time from the image pickup unit.
- (8) In the image pickup system defined by any one of Para. (1) to (7) above, when the image pickup unit obtains picked-up image data for one frame composed of a plurality of pixel rows, the varying control means selects and outputs picked-up image data for a fewer number of pixel rows than the plurality of pixel rows.
- (9) In the image pickup system defined by any one of Para. (1) to (8) above, when the image pickup unit obtains picked-up image data for one frame composed of a plural number of colors, the varying control means selects and outputs data for an arbitrary number of colors from among the picked-up image data.
- (10) In the image pickup system defined by any one of Para. (1) to (9) above, the varying control means is arranged to increase or decrease an amount of information carried by each of pixels with which the image pickup unit forms the picked-up image data.
- (11) An image pickup system is composed of an image pickup unit which has a connection terminal for connection with an external apparatus and which is arranged to pick up an image to output picked-up image data from the connection terminal and at least one external apparatus which is connected to the image pickup unit. The image pickup unit comprises data exchange means for exchanging data with the external apparatus connected, comparison means for making a comparison between an image displaying method of the external apparatus and an image pickup method of the image pickup unit, and varying control means for varying an image pickup action or a picked-up image data output action of the image pickup unit according to a result of the comparison made by the comparison means or according to an operation performed by an operator of the image pickup system.
- (12) An image pickup system is arranged to include, in addition to the arrangement of the system defined by Para. (11) above, display varying means for varying the image displaying method of the external apparatus according to the result of the comparison made by the comparison means or according to the operation performed by the
- to the result of the comparison made by the comparison means or according to the operation performed by the operator of the image pickup system.
- (13) An image pickup system is arranged to include, in addition to the arrangement of the system defined by Para.
  (11) above, informing means for informing one of or all of the operator of the image pickup system, the external apparatus and the image pickup unit of the result of the comparison made by the comparison means.
- (14) In the image pickup system defined by any one of Para. (11) to (13) above, when the image pickup unit obtains a plurality of pixel data, the varying control means selects and outputs at least one pixel data from among the plurality of pixel data.

- (15) In the image pickup system defined by any one of Para. (11) to (14) above, the varying control means is arranged to vary the number of frames of images to be picked up per unit time by the image pickup unit.
- (16) In the image pickup system defined by any one of Para. (11) to (15) above, the varying control means is arranged to select and output picked-up image data for at least one picture from among picked-up image data for a plurality of pictures being sent out at intervals of a predetermined length of time from the image pickup unit.

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- (17) In the image pickup system defined by any one of Para. (11) to (16) above, when the image pickup unit obtains picked-up image data for one frame composed of a plurality of pixel rows, the varying control means selects and outputs picked-up image data for a fewer number of pixel rows than the plurality of pixel rows.
- (18) In the image pickup system defined by any one of Para. (11) to (17) above, when the image pickup unit obtains picked-up image data for one frame composed of a plural number of colors, the varying control means selects and outputs data for an arbitrary number of colors from among the picked-up image data.
- (19) In the image pickup system defined by any one of Para. (11) to (18) above, the varying control means is arranged to increase or decrease an amount of information carried by each of pixels with which the image pickup unit forms the picked-up image data.
- (20) In the image pickup system defined by Para. (11), the image pickup unit includes display speed detection means for detecting or predicting a display speed of an image display device included in the external apparatus connected.
  - (21) In the image pickup system defined by Para. (11), the image pickup unit includes resolution detection means for detecting or predicting a resolution of an image display device included in the external apparatus connected.
  - (22) In the image pickup system defined by Para. (11), the image pickup unit includes color information amount detection means for detecting or predicting an amount of color information to be displayed by an image display device included in the external apparatus connected.
  - (23) An image pickup unit comprises image pickup means for picking up an optical image to form a picked-up image signal, communication means for performing communication with an external signal processing apparatus, and control means for receiving information on a processing capability characteristic of the external signal processing apparatus and changing an image pickup mode of the image pickup means on the basis of the information on the processing capability characteristic.
  - (24) The image pickup unit defined by Para. (23) above is arranged to be removably attachable to the external signal processing apparatus.
  - (25) In the image pickup unit defined by Para. (23) above, the control means is arranged to receive information on an internal operation speed of the external signal processing apparatus.
  - (26) In the image pickup unit defined by Para. (23) above, the control means is arranged to receive information on a display capability of a display device included in the external signal processing apparatus.
  - (27) In the image pickup unit defined by Para. (23) above, the control means is arranged to change the image pickup mode by changing an amount of information per unit time of the picked-up image signal to be formed by the image pickup means.
  - (28) In the image pickup unit defined by Para. (23) above, the control means is arranged to change the image pickup mode by changing an amount of color information of the picked-up image signal to be formed by the image pickup means.
  - (29) A picked-up image signal processing apparatus comprises communication means for performing communication with an image pickup unit including image pickup means for picking up an optical image to form a picked-up image signal, and control means for transmitting to the image pickup unit a processing capability characteristic of signal processing means included in the picked-up image signal processing apparatus and controlling and changing an image pickup mode of the image pickup means included in the image pickup unit according to the processing capability characteristic of the signal processing means.
  - (30) In the picked-up image signal processing apparatus defined by Para. (29) above, the image pickup unit is arranged to be removably attachable to the picked-up image signal processing apparatus.
  - (31) In the picked-up image signal processing apparatus defined by Para. (29) above, the control means is arranged to transmit information on an operation speed of the signal processing means to the image pickup unit.
- (32) In the picked-up image signal processing apparatus defined by Para. (29) above, the control means is arranged to transmit information on a display capability of the signal processing means to the image pickup unit.
  - (33) In the picked-up image signal processing apparatus defined by Para. (29) above, the control means is arranged to change the image pickup mode by changing an amount of information per unit time of the picked-up image signal to be formed by the image pickup unit.
- (34) In the picked-up image signal processing apparatus defined by Para. (29) above, the control means is arranged to change the image pickup mode by changing an amount of color information of the picked-up image signal to be formed by the image pickup unit.

Preferred embodiments of the invention are provided by the arrangements described above.

Further, in an image pickup system composed of at least one computer which has at least one connection terminal and at least one image pickup unit which is detachably connectable to the connection terminal, the image pickup unit connected to the connection terminal of the computer comprises means for exchanging data with the computer, means for measuring or predicting a processing speed of the computer, means for making a comparison between the processing speed and an image pickup speed of the image pickup unit, and means for varying an image pickup action of the image pickup unit according to a result of the comparison.

Further, in an image pickup system composed of at least one computer which has at least one connection terminal and at least one image pickup unit which is detachably connectable to the connection terminal, the image pickup unit connected to the connection terminal of the computer comprises means for exchanging data with the computer, means for making a comparison between an image display method of the computer and an image pickup method of the image pickup unit, and means for varying an image pickup action of the image pickup unit according to a result of the comparison.

The provision of these means arranged according to the invention enables the image pickup system to fully utilize the features and performance of the computer and also to solve the problems resulting from differences relative to the data processing speed and the display device of the computer.

The above and further advantages and features of the invention will become apparent from the following detailed description of embodiments thereof taken in conjunction with the accompanying drawings.

### 20 Brief Description of the Drawings:

Fig. 1 is a block diagram showing the arrangement of a first embodiment of the invention.

Fig. 2 is a block diagram showing the arrangement of an image pickup unit of the first embodiment.

Fig. 3 is a flow chart showing an image pickup operation for one frame in the first embodiment.

Fig. 4 is a flow chart showing a moving image pickup routine A in the first embodiment.

Fig. 5 is a flow chart showing a moving image pickup routine B in the first embodiment.

Fig. 6 is a flow chart showing an image pickup operation of a third embodiment of this invention.

Fig. 7 is a block diagram showing by way of example the conventional image pickup system.

### 30 Detailed Description of the Preferred Embodiments:

Preferred Embodiments of the invention are described below with reference to the drawings.

### (First Embodiment)

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A first embodiment of the invention is described with reference to Figs. 1 and 2 as follows.

Fig. 1 is a block diagram showing an image pickup system arranged according to the invention as the first embodiment of the invention. Fig. 2 is a block diagram showing an image pickup unit of the first embodiment.

Referring to Fig. 1, the illustration includes an image pickup unit 1, a device unit 2 which is of connection specifications equivalent to those of the image pickup unit 1, a computer 3, a CPU 4 of the computer 3, connection terminals 5 and 6 of the computer 3, a display device 7 of the computer 3, a memory device 8 of the computer 3, and an operation program 9 of the CPU 4.

Referring to Fig. 2 which shows in a block diagram the arrangement of the image pickup unit 1, the illustration includes a lens unit 10, a CCD 11, an A/D converter 12, a digital signal processing device (DSP) 13, a FIFO memory 14, a lens controller 15 which controls the lens unit 10 and includes an automatic focusing device and an automatic image stabilizing (image-shake preventing) device which are known, a timing generator (TG) 16 arranged to send out timing pulses to the CCD 11 and the A/D converter 12, a control unit 17 disposed within the image pickup unit 1, an interface (camera I/F) 18 provided for external connection, a light unit 19 arranged at the image pickup unit 1 to illuminate an object of shooting, and a counter 20 arranged to divide the frequency of input clock pulses and outputs frequency-divided clock pulses (to be used in a second embodiment).

The image pickup system picks up images with the image pickup unit 1 connected to the computer 3.

# (Pickup of Still Image)

An operation of picking up an image for one frame is first described with reference to Figs. 1 and 2 and Fig. 3 which is a flow chart. The control unit 17 of the image pickup unit 1 controls this operation. Various control actions performed at steps S11 to S17 shown in Fig. 3 will be described.

At the step S11, the control unit 17 causes the CCD 11 to measure the luminance of an object of shooting. After

that, the light unit 19 is controlled to illuminate the object to give a condition best suited for taking a shot.

At the step S12, the lens unit 10 is caused through the lens controller 15 to perform a focusing action. The image stabilizing device is also used if necessary.

At the step S13, image information for one frame is stored as electric charge at the CCD 11 through the lens unit 10. This control is performed by the control unit 17. The timing of reading from the CCD 11 is decided by timing pulses sent from the TG 16. The electric charge storing time of the CCD 11 is decided by the control unit 17 according to the luminance of the object obtained at the step S11.

At the step S14, the A/D converter 12 is caused to read out image data for one frame stored at the CCD 11. A digital image signal obtained by the A/D converter 12 is supplied to the DSP 13 to be converted into a Y (luminance) signal and color-difference signals. These signals are converted further into R, G and B signals. The A/D converting speed of the A/D converter 12 and the operation of the CCD 11 are decided by the timing pulses sent from the TG 16. The TG 16 has different operation pulse output modes including a mode 0 to a mode 3.

In the mode 0, a signal for one frame is taken in every time a control signal is received from the control unit 17. In the mode 1, operation pulses are sent to the CCD 11 and the A/D converter 12 in such a way as to cause picked-up image data for five frames to be outputted per sec from the DSP 13. In the mode 2, operation pulses are sent to the CCD 11 and the A/D converter 12 in such a way as to cause picked-up image data for fifteen frames to be outputted per sec from the DSP 13. In the mode 3, operation pulses are sent to the CCD 11 and the A/D converter 12 in such a way as to cause picked-up image data for thirty frames to be outputted per sec from the DSP 13. In the case of Fig. 3, the flow of operation is assumed to be executed in the mode 0.

At the step S15, the DSP 13 is caused to process the output of the A/D converter 12. In this case, the Y and colordifference signals are converted into R, G and B signals. The DSP 13 has R, G and B outputs. From these outputs, the R, G and B signals are simultaneously outputted at a time on a line-by-line basis. In this case, one frame consists of 250 lines.

At the step S16, signals outputted from the DSP 13 are temporarily stored in the FIFO memory 14, which has a storage capacity of three frames.

At the step S17, the signals are read out from the FIFO memory 14 and sent to the computer 3 through the interface 18.

A still image for one frame can be obtained through the steps S11 to S17 described above.

In the computer 3, the image data obtained from the image pickup unit 1 is displayed on the display device 7 and, at the same time, is stored in the memory device 8. If necessary, the computer 3 transfers the image data to the device unit 2. The operation of the computer 3 is decided by the operation program 9.

(Pickup of Moving Image)

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In the case of this embodiment, the image pickup system is capable of taking a moving image by continuously taking still images as described above. The moving image taking operation is next described below with reference to Figs. 1, 2, 4 and 5.

In taking a moving image, the flow of operation of the image pickup system is divided into a routine A and a routine B. In the routine A, picked-up image data read out from the CCD 11 is continuously written into the FIFO memory 14. In the routine B, the picked-up image data is read out from the FIFO memory 14 and is sent out continuously to the computer 3 through the interface 18. The control unit 17 simultaneously executes the routine A and the routine B. By performing the routine A and the routine B, an image pickup operation can be carried on in a manner suited to the processing speed of the computer 3. The routine A is as shown in a flow chart in Fig. 4, while the routine B is shown also in a flow chart in Fig. 5.

The routine A is first described with reference to Figs. 1, 2 and 4 as follows.

At a step S21, the routine A begins. The following actions are all executed by the control unit 17.

At a step S22, picked-up image data for one frame is obtained in the same manner as the still image taking procedures described above. The image data thus obtained is stored in the FIFO memory 14.

At a step S23, a check is made for a vacancy in the storage capacity of the FIFO memory 14. The FIFO memory 14 of the image pickup unit 1 is capable of storing image data for three frames. When image data for three frames has been written in the FIFO memory 14, the FIFO memory sends a flow signal to the control unit 17. The control unit 17 can find if there is a vacancy in the FIFO memory 14 through the flow signal.

Since the control unit 17 is arranged to execute both the routine A which is for writing into the FIFO memory 14 and the routine B which is for reading from the FIFO memory 14, the flow signal being sent from the FIFO memory 14 indicates that the action of reading from the FIFO memory 14 is slower than the action of writing into the FIFO memory 14. In other words, in such a case, the amount of image data picked up per unit time is larger than that of image data processed by the computer 3. Then, in this case, it is necessary to decrease the amount of image data picked up per unit time.

If the flow signal is detected at the step \$23, the flow comes to a step \$26. If not, the flow comes to a step \$24,

At the step S24, a check is made to find if a request for stopping the image pickup operation is received from the computer 3. If so, the flow comes to a step S25. If not, the flow comes back to the step S22 to continue the image pickup operation.

At the step S25, the routine A comes to an end. The image pickup operation at the CCD 11 is brought to a stop. At the same time, the lens unit 10, the CCD 11, the A/D converter 12, the DSP 13, the lens controller 15, the TG 16 and the light unit 19 stop from operating.

When the flow proceeds to the step S26, there are two modes for decreasing the amount of image data to be picked up per unit time. In one mode, the operator of the image pickup system decides to decrease the amount of image data picked up per unit time and gives an instruction for the execution of the decision. In the other mode, the image pickup unit 1 automatically decreases the amount of image data picked up per unit time. A choice between the two methods is set in the program 9 beforehand. In the case of the instruction from the operator, the flow comes to a step S27. In the case of the automatic execution by the image pickup unit 1, the flow proceeds to a step S28.

At the step S27, the current output mode of the TG 16 is changed by the operator to another mode which gives a suitable value among the output modes of the TG 16 mentioned in the foregoing description of the step S14 of the still image taking operation. As a result of the operation by the operator, the amount of picked-up image data to be sent out per unit time from the image pickup unit 1 to the computer 3 decreases. The flow then comes from the step S27 to a step S31.

At the step S28, the number of the output mode of the TG 16 mentioned in the foregoing description of the step S14 of the still image taking operation is decremented by one. In other words, with the current output mode of the TG 16 assumed to be the mode 3, the mode 3 is changed over to the mode 2. This change causes the amount of pickedup image data per unit time to decrease. Incidentally, the initial value of the mode is 3.

The image pickup unit 1 informs the computer 3 of the above-stated action when the output mode of the TG 16 is lowered. The computer 3 then displays this action on the display device 7.

At a step S29, a check is made to find if the output mode of the TG 16 has become the mode 0. If so, the mode 0 indicates that no moving image can be taken by the image pickup system. This result of check is obtained in a case where the picked-up image data reading speed of the computer 3 has lowered or when it is incapable of reading the data. If the output mode of the TG 16 is found to be the mode 0, the flow comes to a step S30. If not, the flow comes to the step S31.

At the step S30, an error processing action to be carried out in the event of the mode 0 is executed. The control unit 17 informs the computer 3 that the moving image taking action is impossible, and the flow comes to a step S25 to bring the routine A to an end.

At the step S31, the data currently stored in the FIFO memory 14 is read out by the routine B and a check is made for any vacancy in the storage capacity of the FIFO memory 14. If the flow signal is detected, the flow comes to a step S32. If not, the flow comes to the step S22.

At the step S32, the operation is suspended for a predetermined period of time. After that, the flow comes to the step S31 again to make a check for any vacancy in the storage capacity of the FIFO memory 14.

The routine B is next described with reference to Figs. 1, 2 and 5 as follows.

At a step S41, the routine B begins. The following actions are all executed by the control unit 17:

At a step S42, a check is made for the state of the FIFO memory 14. The FIFO memory 14 sends an empty' signal to the control unit 17 if it has no picked-up image data stored there at all. If the empty signal is detected, the flow comes to a step S43. If not, the flow comes to a step S47.

At the step S43, the flow of operation is suspended for a predetermined period of time to wait until the picked-up image data is stored in the FIFO memory 14.

At a step S44, check is made for a state of error. In other words, in a case where the action of the step S43 continues to a predetermined extent without executing the action of the step S47, this state indicates that the image pickup operation according to the routine A has not been performed at all. If this state is detected, the flow comes to a step S45. If not, the flow comes back to the step S42.

At the step S45, the error processing action is performed. The computer 3 is informed that the image pickup operation cannot be continued due to occurrence of an error. After the step S45, the flow comes to a step S46 to bring the routine B to an end.

When the flow comes from the step S42 to the step S47, the picked-up image data stored in the FIFO memory 14 is read out.

At a step S48, the picked-up image data read out at the step S47 is sent out to the computer 3.

(Second Embodiment)

An image pickup system which is a second embodiment of the invention is arranged in the same manner as the

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first embodiment and as shown in Figs. 1 and 2. The operation of the second embodiment in each part is, however, not exactly the same as in the first embodiment. The still image taking operation of the second embodiment is the same as that of the first embodiment described in the foregoing. Therefore, the following description of the second embodiment omits its still image taking operation and covers only its moving image taking operation.

(Pickup of Moving Image)

When the image pickup unit 1 is connected to the computer 3, the image pickup unit 1 receives through the interface 18 an operation clock signal Clk0 from the computer 3. The operation clock signal Clk0 is of a frequency which is proportional to the processing speed of the computer 3. The operation clock signal Clk0 is inputted to the counter 20 from the interface (I/F) 18. The counter 20 is provided with a means for detecting the frequency Fc of the operation clock signal Clk0. Information on the frequency Fc detected is sent to the control unit 17.

The counter 20 receives from the control unit 17 a signal Oc which has a higher frequency than the signal Clk0 and uses it in measuring the frequency Fc. The frequency Fc of the signal Clk0 is measured by counting a number of times for which the signal Oc varies in one cycle of the signal Clk0. Information on the measured frequency Fc is stored at the control unit 17. If the intrinsic frequency Fc of the computer 3 is known, the value of the intrinsic frequency Fc may be stored beforehand at the control unit 17.

Then, the control unit 17 compares the frequency Fc with the output mode of the TG 16 which is arranged as mentioned at the step S14 of the foregoing description of the still image taking operation of the first embodiment. The output mode of the TG 16 is changed over to another output mode according to the result of the comparison.

The amount of image data picked up per unit time by the image pickup unit 1 can be adjusted to the processing speed of the computer 3 by this operation.

(Third Embodiment)

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An image pickup system which is a third embodiment of the invention is described with reference to Figs. 1, 2 and 6 as follows. The image pickup system is arranged in the same manner as the first embodiment described in the foregoing. However, its operation in each part differs from that of the first embodiment.

The image pickup unit 1 is connected to the computer 3 as shown in Figs. 1 and 2. Then, the CPU 4 sends information on the display method of the display device 7 to the control unit 17. The control unit 17, which has stored information on an image pickup method used before, sends the information to the CPU 4.

The display method of the display device 7 is assumed to be as follows.

Resolution:

320 horizontal pixels and

Display speed:

240 vertical pixels per frame 10 frames per sec

Amount of information of one pixel:

8 bits.

monochrome

The operation of the image pickup system which is the third embodiment of the invention is described with reference to the flow chart of Fig. 6 as follows.

At a step S51, the CPU 4 makes a comparison between the image pickup method of the image pickup unit 1 and the display method of the display device 7. Here, the image pickup method of the image pickup unit 1 is assumed to be as follows.

Resolution:

640 horizontal pixels and

480 vertical pixels per frame

Image pickup speed:

30 frames per sec

Amount of information of one pixel:

color, 8 bits for each of colors R, G and B, 24 bits in all

The CPU 4 informs the operator of the image pickup system of the display method of the display device 7 and the image pickup method of the image pickup unit 1.

At a step S52, depending on whether the operation is performed by the operation program 9 or by the operator of the image pickup system, either of the following actions (a) and (b) is selected.

- (a) The image pickup method of the image pickup unit 1 is matched to the display method of the display device 7.
- (b) The display method of the display device'7 is matched to the image pickup method of the image pickup unit 1.

If the display method of the display device 7 is fixed, the action (a) is selected and the flow comes to a step S53. If the action (b) is selected, the flow comes to a step S56.

At the step S53, the DSP 13 performs a processing to match the number of pixels of the picked-up image data outputted from the image pickup unit 1 to the display method of the display device 7. Since the number of pixels of the picked-up image data is larger than the number of pixels that can be displayed by the display device 7 in this instance, the numbers of pixels both in the vertical and horizontal directions are respectively reduced to one half.

At a step S54, the DSP 13 causes the amount of information carried by each pixel of the picked-up image data to be matched to the amount of information that can be displayed by the display device 7. In the case of this embodiment, the display device 7 is capable of displaying only in monochrome and the amount of information of each pixel of it is only 8 bits. The amount of information of each pixel of the picked-up image data is, on the other hand, 24 bits. In this case, therefore, only the data of color G (8 bits) of the picked-up image data is sent to the display device 7.

At a step S55, the DSP 13 causes the frame speed of the picked-up image data to be matched to the display speed of the display device 7. Since the display speed of the display device 7 is 10 frames/sec while the image pickup speed of the image pickup unit 1 is 30 frames/sec in this case, picked-up image data of one of every three frames is selected and sent to the display device 7.

At the step S56, the display method of the display device 7 is matched to the image pickup method of the image pickup unit 1. It might be impossible to display the whole amount of information carried by the picked-up image data. However, this action (b) is selectable in a case where, for example, the whole picked-up image data is stored in the memory device 8 without displaying the picked-up image data in its entirety.

The flow of operation comes to an end at a step S57.

The image pickup method of the image pickup unit 1 is matched to the display method of the display device 7 by the steps S51 through S56. After completion of the matching process, the image pickup unit 1 is allowed to perform the image pickup operation.

As apparent from the foregoing description, a means for controlling the image pickup mode of the image pickup unit 1 may be disposed either within the image pickup unit 1 or on the side of the computer 3 which is serving as an external picked-up image signal processing means.

According to the arrangement of the embodiments described above, the function of processing the picked-up image signal formed by the image pickup unit and the function of controlling the image pickup operation are arranged to be performed in part within the external picked-up image signal processing apparatus. The arrangement, therefore, permits reduction of the size of the image pickup unit, so that the image pickup unit can be formed in a card-like shape, such as a card of the PCMCIA standards, like in the case of the embodiments described above.

The conventional method of processing a picked-up image signal with a computer or the like has necessitated a process of converting the picked-up image signal into a signal conforming to the television format of the NTSC system or the like before converting it into a digital signal for the computer. The conventional method thus involves some duplicating part in processing the signal. Such wasteful process can be avoided according to the arrangement of the embodiments described above.

Further, according to the arrangement of the embodiments of the invention, an image pickup function can be added to a signal processing apparatus such as a computer without necessitating any complex arrangement.

It is particularly advantageous feature of the image pickup system that the capability of the image pickup unit is adjusted to the signal processing capability such as the signal processing speed and the display capability of the signal processing apparatus. In accordance with the invention, therefore, the signal processing operation can be optimized to eliminate any wasteful process. The invention, therefore, gives a system which processes signals at an optimum speed and also reduces the power consumption of the whole system.

### Claims

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 An image pickup system composed of an image pickup unit which has a connection terminal for connection with an external apparatus and which is arranged to pick up an image to output picked-up image data from the connection terminal and at least one external apparatus which is connected to said image pickup unit,

said image pickup unit comprising:

data exchange means for exchanging data with said external apparatus connected;

processing-speed detection means for measuring or predicting a processing speed of said external apparatus connected;

speed comparison means for making a comparison between the processing speed of said external apparatus detected by said processing-speed detection means and an image pickup speed or a picked-up image data output speed of said image pickup unit; and

varying control means for varying an image pickup action or a picked-up image data output action of said image pickup unit according to a result of the comparison made by said speed comparison means or according to an operation performed by an operator of said image pickup system.

- 2. A system according to claim 1, further comprising Dm detection means for measuring or predicting a maximum amount (Dm) of picked-up image data transferable per unit time to said external apparatus connected, and data amount comparison means for making a comparison between the detected maximum amount (Dm) of picked-up image data and an amount (Sp) of picked-up image data being outputted per unit time by said image pickup unit.
- 3. A system according to claim 1 or claim 2, further comprising operation clock detection means for measuring or predicting an operation clock speed of said external apparatus, and wherein said speed comparison means is arranged to compare the image pickup speed of said image pickup unit with the operation clock speed of said external apparatus measured or predicted by said operation clock detection means.
- 4. An image pickup system composed of an image pickup unit which has a connection terminal for connection with an external apparatus and which is arranged to pick up an image to output picked-up image data from the connection terminal and at least one external apparatus which is connected to said image pickup unit,
  - said image pickup unit comprising:

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- data exchange means for exchanging data with said external apparatus connected; comparison means for making a comparison between an image displaying method of said external apparatus and an image pickup method of said image pickup unit; and
- varying control means for varying an image pickup action or a picked-up image data output action of said image pickup unit according to a result of the comparison made by said comparison means or according to an operation performed by an operator of said image pickup system.
- 5. A system according to claim 4, further comprising display varying means for varying the image displaying method of said external apparatus according to the result of the comparison made by said comparison means or according to the operation performed by the operator of said image pickup system.
- 6. A system according to claim 1 or claim 4, further comprising informing means for informing one or all of the operator of said image pickup system, said external apparatus and said image pickup unit of the result of the comparison made by said comparison means.
- 7. A system according to any one of claims 1 or 4 to 6, wherein, when said image pickup unit obtains a plurality of pixel data, said varying control means selects and outputs at least one pixel data from among the plurality of pixel data
  - 8. A system according to any one of claims 1 or 4 to 7, wherein said varying control means is arranged to vary the number of frames of images to be picked up per unit time by said image pickup unit.
    - 9. A system according to any one of claims 1 or 4 to 8, wherein said varying control means is arranged to select and output picked-up image data for at least one picture from among picked-up image data for a plurality of pictures being sent out at intervals of a predetermined length of time from said image pickup unit.
    - 10. A system according to any one of claims 1 or 4 to 9, wherein, when said image pickup unit obtains picked-up image data for one frame composed of a plurality of pixel rows, said varying control means selects and outputs picked-up image data for a fewer number of pixel rows than the plurality of pixel rows.
  - 11. A system according to any one of claims 1 or 4 to 10, wherein, when said image pickup unit obtains picked-up image data for one frame composed of a plural number of colors, said varying control means selects and outputs data for an arbitrary number of colors from among the picked-up image data.
- 12. A system according to any one of claims 1 or 4 to 11, wherein said varying control means is arranged to increase or decrease an amount of information carried by each of pixels with which said image pickup unit forms the picked-up image data.
  - 13. A system according to claim 4, wherein said image pickup unit further includes display speed detection means for

detecting or predicting a display speed of an image display device included in said external apparatus connected.

- 14. A system according to claim 4, wherein said image pickup unit further includes resolution detection means for detecting or predicting a resolution of an image display device included in said external apparatus connected.
- 15. A system according to claim 4, wherein said image pickup unit further includes color information amount detection means for detecting or predicting an amount of color information to be displayed by an image display device included in said external apparatus connected.
- 10 16. An image pickup unit comprising:

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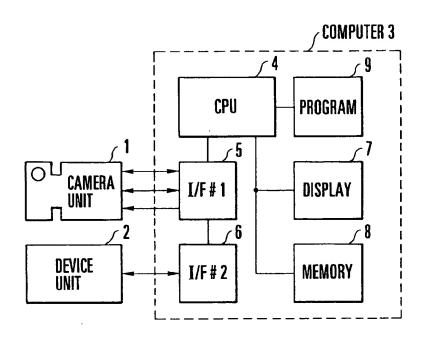
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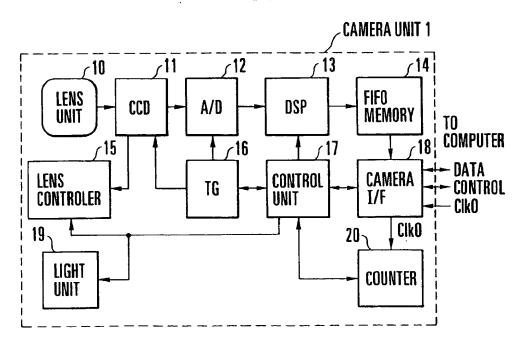
image pickup means for picking up an optical image to form a picked-up image signal; communication means for performing communication with an external signal processing apparatus; and control means for receiving information on a processing capability characteristic of said external signal processing apparatus and changing an image pickup mode of said image pickup means on the basis of the information on the processing capability characteristic.

- 17. A unit according to claim 16, wherein said image pickup unit is arranged to be removably attachable to said external signal processing apparatus.
- 18. A unit according to claim 16, wherein said control means is arranged to receive information on an internal operation speed of said external signal processing apparatus.
- 19. A unit according to claim 16, wherein said control means is arranged to receive information on a display capability of a display device included in said external signal processing apparatus.
  - 20. A unit according to claim 16, wherein said control means is arranged to change the image pickup mode by changing an amount of information per unit time of the picked-up image signal to be formed by said image pickup means.
- 30 21. A unit according to claim 16, wherein said control means is arranged to change the image pickup mode by changing an amount of color information of the picked-up image signal to be formed by said image pickup means.
  - 22. A picked-up image signal processing apparatus comprising:
- communication means for performing communication with an image pickup unit including image pickup means for picking up an optical image to form a picked-up image signal; and control means for transmitting to said image pickup unit a processing capability characteristic of signal processing means included in said picked-up image signal processing apparatus and for controlling an image pickup mode of said image pickup means included in said image pickup unit according to the processing capability characteristic of said signal processing means.
  - 23. An apparatus according to claim 22, wherein said image pickup unit is arranged to be removably attachable to said picked-up image signal processing apparatus.
- 24. An apparatus according to claim 22, wherein said control means is arranged to transmit information on an operation speed of said signal processing means to said image pickup unit.
  - 25. An apparatus according to claim 23, wherein said control means is arranged to transmit information on a display capability of said signal processing means to said image pickup unit.
  - 26. An apparatus according to claim 23, wherein said control means is arranged to change the image pickup mode by changing an amount of information per unit time of the picked-up image signal to be formed by said image pickup unit.
- 27. An apparatus according to claim 23, wherein said control means is arranged to change the image pickup mode by changing an amount of color information of the picked-up image signal to be formed by said image pickup unit.

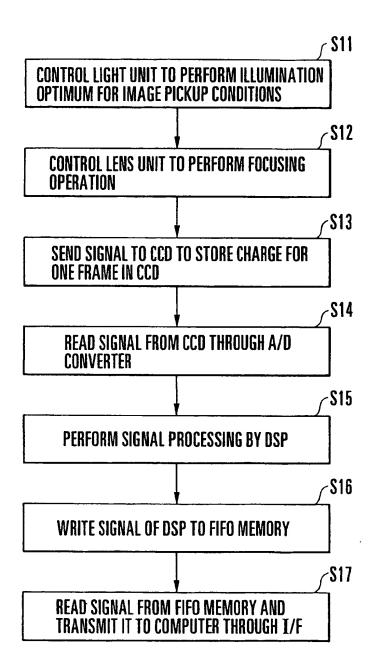
F I G. 1



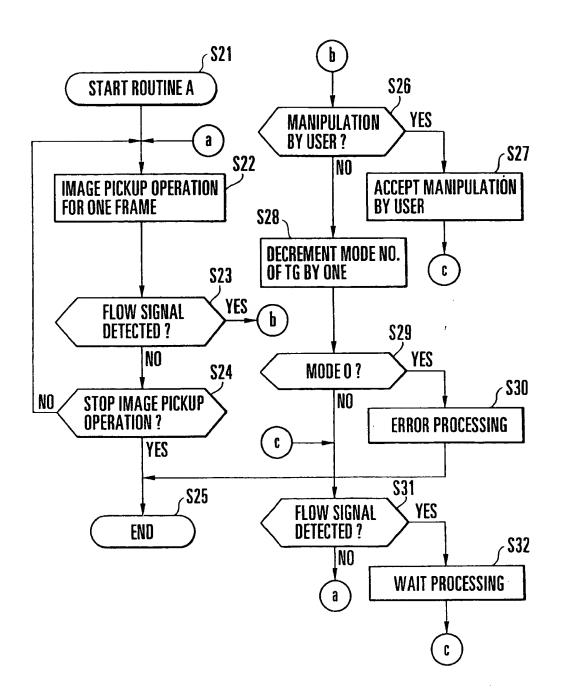
F I G. 2



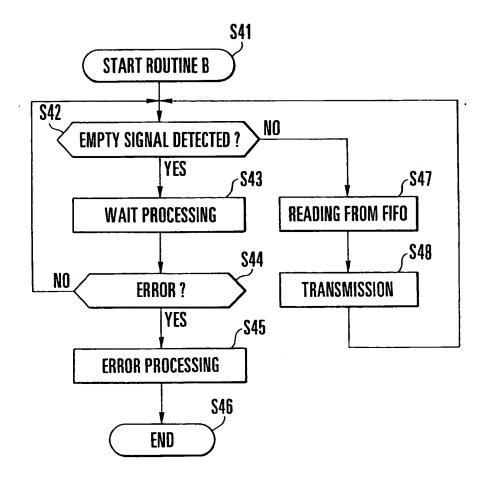
F I G. 3



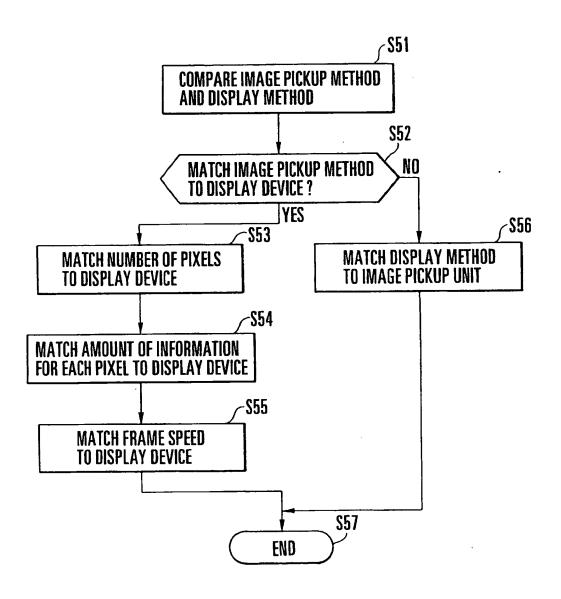
F I G. 4



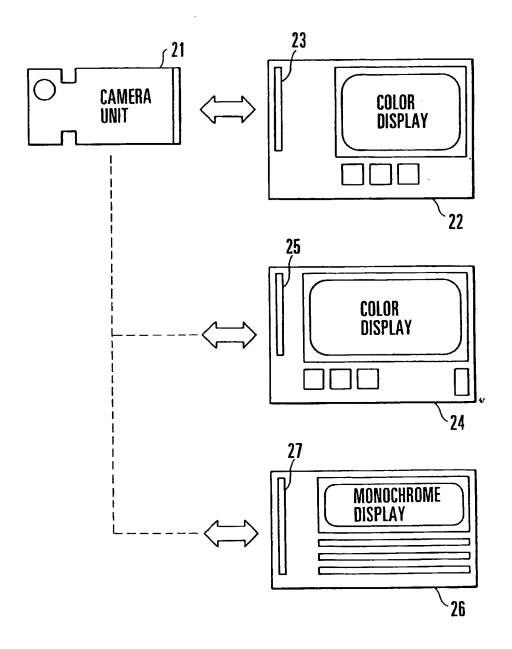
F I G. 5



F I G. 6



F I G. 7



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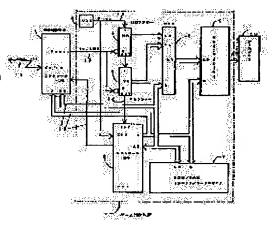
KITANI YUKIYA KAWAGISHI HIROSHI INABA ATSUSHI KATOU TETSUYA

# (54) APPLYING METHOD OF GAME SYNCHRONIZATION OF COMMUNICATION GAME MACHINE

(57)Abstract:

PURPOSE: To eliminate the control timing of the different time series of the game machines so as to synchronize the control timing, by resetting cyclic synchronizing counters to manage the control cycle of the game by the reset instruction received by a communication means.

CONSTITUTION: When a reset signal 13 is included to the parent and output to all the game control devices 2 almost at the same time by a communication control device 1, the cyclic horizontal and vertical synchronizing counters 4 and 5 of the game control devices 2 to carry out a communication competition game are reset almost at the same time. As a result, the phases of the cynchronizing counters 4 and 5 of the plural game devices 2 are to be arranged in order within a specific scope, and an operation data transmitted and received in the cycles of the counters 4 and 5 are considered as a pair of data of the same time in the time series. That is, the pair of data of the time series of the game control devices 2 of the competition opponents are transmitted at the same time relatively in the scope of the synchronization, so as to generate no discrepancy between both sides.



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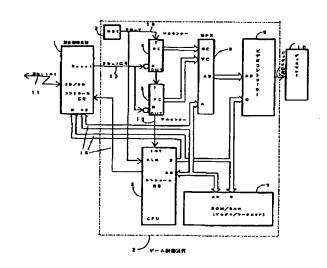
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# (54)【発明の名称】 通信ゲーム機のゲームの同期の取り方

## (57)【要約】

【目的】 通信機能を備えた複数のゲーム機どうしを、 LANや電話回線や通信ケーブルに接続し、通信をしな がら対戦ゲームを行う際に、ゲームの進捗の同期を取る 方法を提供する。

【構成】 通信手段と、ゲームを制御する周期的な同期カウンターを備えた複数のゲーム機どうしで、通信をしながら通信対戦ゲームを行う場合、対戦ゲーム機の中の一台が親機となり、他のゲーム機が子機となり、その親機のゲーム機より自らの同期カウンターにリセット指令を出すと共に、通信手段によりリセット指令を他の子機のゲーム機に一斉に送信する機能を備え、また子機のゲーム機は、その通信手段により受信したリセットするリセット手段を備えて構成され、リセット指令により全てのゲーム機の制御の位相が等しくなるようにした、通信ゲーム機装置。



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### 【特許請求の範囲】

【請求項1】 通信手段と、ゲームの制御周期を司る周期的な同期カウンター4、5を備えたゲーム制御装置2に於いて、その通信手段によって受信したリセット指令14、13により、ゲームの制御周期を司る周期的な同期カウンター4、5をリセットするリセット手段を備えた事を特徴とするゲーム制御装置2。

【請求項2】 請求項1記載のゲーム制御装置2を、通信ケーブルにより複数台接続した通信対戦ゲーム機システムに於いて、親機となったゲーム制御装置2は、自ら 10の同期カウンター4、5に同期して自らの同期カウンター4、5にリセット指令13を出すとともに、通信手段により他の子機のゲーム機制御装置2にリセット指令14を一斉に送信するようにした、請求項1記載のゲーム機制御装置システム。

### 【発明の詳細な説明】

### [0001]

【産業上の利用分野】本発明は、通信機能を備えた複数のゲーム機どうしをLANや電話回線や通信ケーブル等のネットワークに接続し、通信をしながら対戦ゲームを 20行うゲーム機制御装置に関する。

### [0002]

【従来の技術】従来のゲーム機制御装置は、ゲームの進行を制御する周期カウンターを持ち、この周期カウンターに同期してゲームの進行が制御されていた。通信制御もこのような周期カウンターに同期して制御されていた。又、この周期カウンターはリセット端子を持たず自走しているカウンターであり、対戦相手のゲーム機とは非同期で動いていた。即ち、対戦相手のゲーム機とは周期カウンターの周期の位相は当然異なっていた。

【0003】例えば、ビデオゲーム機の場合、垂直同期カウンターを備えていて、この垂直同期カウンターの周期のタイミングでゲームの進行が制御されているが、各々のゲーム機の垂直同期カウンターは独立に動いていて、各々のゲーム機のカウンターの周期の位相はバラバラであった。これらの問題を無くするため、一般の通信網においては、共通のクロックを設けそのクロックに合わせ網全体の同期をとる手段がとられていた。

### [0004]

【本発明が解決しようとする課題】 2 台以上のゲーム機 40 が、通信で格闘対戦ゲームを行う場合に、一方のゲーム機は他方のゲーム機の操作情報を必要とし、その二つの操作情報に基づいて双方のゲーム機で処理をした結果は、双方のゲーム機で同じ結果とならねばならない。即ち、ゲーム機のこれらの操作情報は時系列的な情報であり、送り手側のゲーム機の時系列な操作情報と受けて側のゲーム機の時系列な制御情報の二つの情報を比較する対が、双方で食い違って異なった処理結果を出してはならない。

【0005】しかしながら、従来は対戦相手のゲーム機 50 ミングを作る周期的なカウンターである。垂直同期カウ

とは非同期で動いていたので、対戦相手とは異なった周期の時系列で送信をする事となり、送信した操作情報と受信した操作情報の対は、双方のゲーム機では時系列的にずれて異なる事が起きた。その結果、双方のゲーム機の判断が食い違うと言った問題点があった。その結果、格闘対戦を行う各々のゲーム機の進捗状況が同じであるべきところが、異なった進捗状況となると言った問題点があった。本発明の目的は、上記のような非同期に起因する、各々のゲーム機の時系列の異なる制御タイミングをなくし、制御のタイミングを一定の範囲内に合わせる

### [0006]

同期をとる事を目的とする

【課題を解決するための手段】上記目的を達成するために本発明は、通信手段と、ゲームの制御タイミングを制御する周期的な同期カウンターを備えた複数のゲーム機どうしで、通信をしながら通信対戦ゲームを行う場合、対戦ゲーム機の中のいずれか一台が親機となり、他のゲーム機が子機となり、その親機のゲーム機より自らの同期カウンターにリセット指令を出すとともに、通信手段又は専用信号線によりリセット指令を他の子機のゲーム機に一斉に送信する機能を備え、また子機のゲーム機は、その通信手段により受信したリセット指令により、周期的な同期カウンターをリセットするリセット手段を備えて構成される。

### [0007]

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【作用】上記手段により、リセット指令を親を含め全てのゲーム機にほぼ同時に出すことにより、リセット指令を受信した通信対戦ゲームをする各ゲーム機の周期的な同期カウンターは、ほぼ同時にある一定の誤差の範囲内でリセットがかかる事となる。このことにより複数のゲーム機の同期カウンターの位相が一定の誤差の範囲内で揃う事になり、したがってその同期カウンターの周期内に送受信された操作情報は時系列的に同時の対の情報の対は、周期の範囲内で相対的に同時に伝わる事になり、時系列の情報の対は双方で食い違う事が無くなる。したがってゲームの進捗も異なることも無くなる。

### [0008]

【実施例】本発明の詳細について実施例に基づいて説明する。図1は本発明の第一実施例の構成を示すプロック図である。本実施例ではビデオゲームの例で説明する。1は通信制御装置(CCU)であり、2はゲーム制御装置であり、3はクロック発生器、4は水平同期カウンター、5は垂直同期カウンター、6はCPU、7はROM/RAM、8はマルチプレクサー、9はヒデオコントロラー、10はデスプレーである。

【0009】水平同期カウンター4と垂直同期カウンター5は、クロック発生器3のクロック16を入力としてデイスプレー10の同期信号の発生とゲームの制御タイミングを作る周期的なカウンターである。垂直同期カウ

3

ンター5の出力信号であるV割り込み信号12はCPU 6の割り込みに入力され、この割り込みの周期によりゲ ームの制御周期を制御している。CPU6はROM/R AM7に格納されたゲームプログラムやゲームデータに 基づき、V割り込み信号12に同期して、ビデオコント ローラー9を制御し、ゲームの進行の制御を行ってい る。また、通信制御装置1はCPU6の制御指令15に より通信ライン11を介して他のゲーム機と通信をおこ なう。マルチプレクサー8はビデオコントローラー9を 制御するアドレスを切り替え画面表示の絵のコントロー 10 でリセットコマンド14を全てのゲーム機にほぼ同時に ルを行う。通信制御装置1よりのリセット信号13は、 水平同期カウンター4と垂直同期カウンター5のリッセ ト端子に接続され、水平同期カウンター4と垂直同期カ ウンターをリセットする。

【0010】通信で対戦ゲームを行う複数のゲーム機 は、図2に示すように、通信接続装置1を備えたゲーム 制御装置2を、通信ライン11を介して接続される。通 信で対戦ゲームを行う複数のゲーム機の内、何れか一台 が親機となり、他が子機となる。対戦ゲームが始まる と、親機のCPU6は、自機のV同期信号12に同期し 20 て自らのゲーム制御装置にリセット信号13をだすと共 に、通信制御装置1を介して他の子機のゲーム機にリセ ットコマンド14を送信する。親機のゲーム制御装置2 では、このリセット信号13により水平同期カウンター 4と垂直同期カウンター5をリセットする。また、子機 側の通信制御装置1では、このリセットコマンド14を 受信して自機のゲーム制御装置2の水平同期カウンター 4及び垂直同期カウンター5にリセット信号13を出し てリセットをかける。

【0011】尚、親機よりリセットコマンドを出すの 30 8 は、親機のゲーム制御装置2の周期的なV同期信号12 に同期して出すが、毎回出す必要は無く、ゲーム機が持 つ発信器2の精度に依存するが、同期ずれを起こさない 程度に、時折リセットコマンドを出す。

【0012】尚、親機と子機の決定は、ゲーム機に設け たスイッチ等の設定によって予め決めても良いし、又、 対戦ゲームに参加したゲーム機どうしで、ゲームを開始 するにあたり通信でジャンケンを行って親機を決めても 良い。又、通信制御装置2からのリセット信号13でリ

セットをかけるのは、垂直同期カウンター5だけでも良 い。又、通信ライン11のネットワークはLANであっ ても良いし、電話のように公衆回線であっても良い。 又、図3のように、親機の通信制御装置1の変わりに別 途親機の代行をする専用の通信制御装置1を設けても良 67.

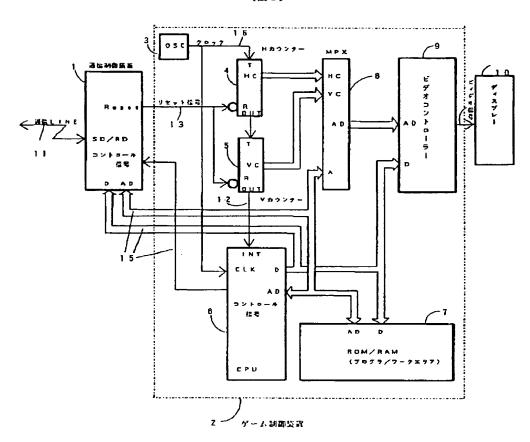
#### [0013]

【発明の効果】上記のように構成する事により、親機の 持つ垂直同期カウンタ5-のV割り込み信号12の周期 送信されるので、全てのゲーム機のV割り込み信号12 の位相が、ほぼそろう事となる。位相がそろった段階 で、この V 割り込み信号 12の 周期内の時間において各 ゲーム機は、操作情報の送信と受信をしあい、操作情報 の交換を行う事により、その周期内の操作情報の対がで き、この対の操作情報を基に各ゲーム機はゲームの進行 の制御を行えば、ゲームの進捗状況が同じとなる。

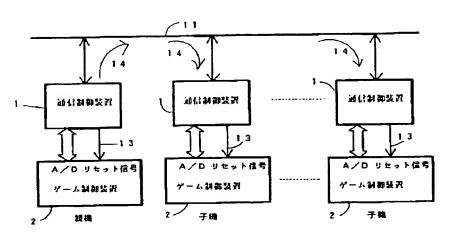
### 【図面の簡単な説明】

- 【図1】通信ゲーム機のプロック図
- 【図2】通信ゲーム機のネットワーク構成図 (例1)
  - 【図3】通信ゲーム機のネットワーク構成図 (例2) 【符号の説明】
  - 通信制御装置
  - ゲーム制御装置
  - クロック発信器 3
  - 水平同期カウンター
  - 垂直同期カウンター
  - CPU
  - **ROM/RAMメモリ**
- マルチプレクサー
- ビデオコントローラー
- 10 ディスプレー
- 11 通信ライン
- 12 V割り込み信号
- 13 リセット信号
- 14 リセットコマンド
- 15 制御指令
- 16 クロック

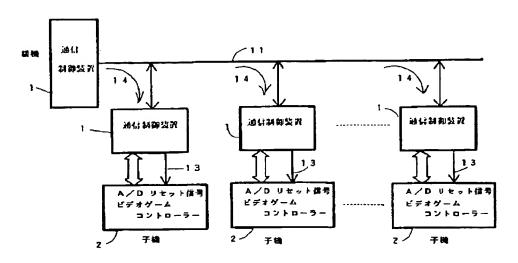
【図1】



[図2]



【図3】



フロントページの続き

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